

# DECIDABILITY OF NEIGHBORHOOD PRODUCTS OF MODAL LOGICS

ANDREY KUDINOV

The products of two modal logics (see [10, 2]) are in many cases undecidable. In [3] it was proved that under some weak restrictions the product of transitive logics is undecidable. In particular any product of logics  $K4, D4, S4$  is undecidable. We show that for neighborhood products of these logics the situation is different. In many cases the neighborhood product of modal logics is decidable and sometimes even is in PSPACE.

A *neighborhood frame* (or an n-frame) is a pair  $\mathcal{X} = (X, \tau)$ , where  $X$  is a nonempty set and  $\tau : X \rightarrow 2^{2^X}$  is the *neighborhood function* of  $\mathcal{X}$ . Sets from  $\tau(x)$  are called *neighborhoods* of point  $x$ . A *neighborhood model* (n-model) is a pair  $M = (\mathcal{X}, V)$ , where  $\mathcal{X} = (X, \tau)$  and  $V$  is a valuation on  $X$ , i.e. a function from the set of all propositional variables to set  $2^X$ . The truth relation  $\models$  on n-models for logical connectives is defined in the classical way and for modalities the definition is the following:

$$M, x \models \Box A \iff \exists U \forall y (y \in U \in \tau(x) \Rightarrow M, y \models A).$$

A formula  $A$  is *valid* on an n-frame  $\mathcal{X}$  if it is true at all points on all models based on  $\mathcal{X}$  (Notation:  $\mathcal{X} \models A$ ). For a class of n-frames  $\mathcal{C}$  formula  $A$  is *valid* on  $\mathcal{C}$  if  $\forall \mathcal{X} \in \mathcal{C} (\mathcal{X} \models A)$ . The set of all formulas that are valid on a given frame (a class of frames) is called the logic of this frame (class of frames). Notations:  $Log(F)$  and  $Log(\mathcal{C})$  respectively.

Any logic of a Kripke frame is normal, i.e. it contains axiom  $\Box(p \rightarrow q) \rightarrow (\Box p \rightarrow \Box q)$  and is closed under the necessitation rule  $\frac{A}{\Box A}$ . Whereas logic of an n-frame is not necessarily normal. For it to be normal  $\tau(x)$  has to be a filter for any  $x \in \mathcal{X}$ . *Filter* is a nonempty set of sets closed under intersections and supersets. From now on we will assume that all n-frames are like this.

N-frames is a more general notion than a Kripke frame. Given a Kripke frame  $F = (W, R)$  we can construct an n-frame  $\mathcal{N}(F) = (W, \tau_R)$ , such that  $\tau_R(x) = \{U \subseteq W \mid R(x) \subseteq U\}$ . Then the validity of formulas will be preserved by this operation.

One of the natural construction that ‘‘increase’’ dimension is the product. For two Kripke frames  $F_1 = (W_1, R_1)$  and  $F_2 = (W_2, R_2)$  their product is a Kripke frame with 2 relations  $F_1 \times F_2 = (W_1 \times W_2, R_1^h, R_2^v)$ , where

$$\begin{aligned} (x, y)R_1^h(z, t) &\iff xR_1z \ \& \ y = t; \\ (x, y)R_2^v(z, t) &\iff x = z \ \& \ yR_2t. \end{aligned}$$

In a similar way we can define the product of two n-frames. Let  $\mathcal{X}_1 = (X_1, \tau_1)$  and  $\mathcal{X}_2 = (X_2, \tau_2)$  be two n-frames. Their product is an n-frame with 2 neighborhood functions:

$$\begin{aligned} \mathcal{X}_1 \times \mathcal{X}_2 &= (X_1 \times X_2, \tau_1^h, \tau_2^v), \text{ where} \\ \tau_1^h(x_1, x_2) &= \{U \subseteq X_1 \times X_2 \mid \exists V (V \in \tau_1(x_1) \ \& \ V \times \{x_2\} \subseteq U)\}; \\ \tau_2^v(x_1, x_2) &= \{U \subseteq X_1 \times X_2 \mid \exists V (V \in \tau_2(x_2) \ \& \ \{x_1\} \times V \subseteq U)\}. \end{aligned}$$

In frames with several relations (neighborhood functions) we use modalities with corresponding sub indexes.

For two unimodal logics  $L_1$  and  $L_2$ , we define the  $n$ -product of them as a logic with two modalities:

$$L_1 \times_n L_2 = \text{Log}(\{\mathcal{X}_1 \times \mathcal{X}_2 \mid \mathcal{X}_1 \models L_1 \ \& \ \mathcal{X}_2 \models L_2\}).$$

The fusion of  $L_1$  and  $L_2$  is the minimal 2-modal logic  $L_1 * L_2$  axiomatized with axioms of  $L_1$  rewritten with  $\Box_1$  and axioms of  $L_2$  rewritten with  $\Box_2$ .

Topological semantics is a particular case of neighborhood semantics for extensions of  $S4$ . For a topological space  $\mathfrak{X} = (X, T)$  we can define neighborhood function

$$\tau(x) = \{U \mid \exists U' \in T(x \in U' \subseteq U)\}.$$

The truth relation on  $\mathfrak{X}$  and on  $\mathcal{X} = (X, \tau)$  will be the same. First paper where topological product was defined was [11]. The authors showed that  $S4 \times_n S4 = S4 * S4$ .

The *derivational* topological semantics (d-semantics) is also a particular case of neighborhood semantics. For a topological space  $\mathfrak{X} = (X, T)$  we can define neighborhood function

$$\tau_d(x) = \{U \mid \exists U' \in T(x \in U' \ \& \ U' \setminus \{x\} \subseteq U)\}.$$

The truth relation on  $\mathfrak{X}$  with d-semantics and on  $\mathcal{X} = (X, \tau_d)$  will also be the same. The results on the d-products of modal logics (the d-logic of the products of topological spaces) can be found in [5]. So the n-frames for extensions of  $K4$  is basically the d-semantics on topological spaces.

Let us put all known completeness results from [7, 11] into a table:

$L_1$	$L_2$	$L_1 \times_n L_2$
$S4$	$S4$	$S4 * S4$
HTC-logic $+\Diamond\top$	HTC logic $+\Diamond\top$	$L_1 * L_2$
HTC-logic	HTC-logic	$L_1 * L_2 + \Delta$
HTC-logic $+\Diamond\top$	HTC-logic	$L_1 * L_2 + \Delta_2$

Notation:

$$\Delta_1 = \{\phi \rightarrow \Box_1 \phi \mid \phi \text{ is closed and } \Box_1\text{-free}\},$$

$$\Delta_2 = \{\psi \rightarrow \Box_2 \psi \mid \psi \text{ is closed and } \Box_2\text{-free}\},$$

$$\Delta = \Delta_1 \cup \Delta_2.$$

A logic  $L$  is called *HTC-logic* (Horn preTransitive Closed logic) if it can be axiomatized by closed formulas and formulas of the type  $\Box p \rightarrow \Box^n p$  or  $p \rightarrow \Box^n p$ .

Logics  $K, D, T, K4, D4, S4$  are all HTC-logics.

**Theorem 1.** *Let  $L_1, L_2 \in \{K, D, T, K4, D4, S4\}$  then the  $n$ -product  $L_1 \times_n L_2$  has fmp and decidable.*

If both logic are serial then their  $n$ -product equals to the fusion and fusion of decidable logics is decidable (see. [2]). The fusion even preserves complexity so in this case the product is PSPACE-complete.

In other cases we need to show that adding  $\Delta$  and  $\Delta_2$  will keep the fmp and the decidability. This is the main result of this paper.

Further work can include studding the exact complexity of these logics. And also the decidability and complexity of other products of modal logics.

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INDIVIDUAL RESEARCHER

*Email address:* kudinov.andrey@iitp.ru