COORDINATISING AFFINE SPATIAL LOGICS

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Logic4Peace 2022



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The general result is as follows [...] assuming [...] a conic [...], we may by means of this conic, by descriptive constructions, divide any line [...] into an infinite series of infnitesimal elements, which are (as a defnition of distance) assumed to be equal; the number of elements between two points [...] measures the distance between the two points [...].





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- Moritz Pasch, a German mathematician
- empirical, natural geometry with an observer at centre
- non-numerical ordering relation of betweenness important

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- Bertrand Russell
- An Essay on the Foundations of Geometry (1897)
- The Principles of Mathematics (1903)



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AN ESSAY ON THE FOUNDATIONS OF GEOMETRY BY BERTRAND A. W. RUSSELL, M.A. FELLOW OF TREATTY COLLEGE, CAMORINGE, CAMBRIDGE: AT THE UNIVERSITY PRESS. 1897 L48 Rights reserved.)



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RUSSELL ON GEOMETRY

- About Cayley: "He showed that, with the ordinary notion of distance, it can be rendered projective [...]. Not content with this, he suggested a new definition of distance [...]; with this definition, the properties usually known as metrical become projective [...]." (FoG)
- About Pasch: "The present subject [i.e. descriptive geometry] is admirably set forth by Pasch [...] with whose empirical pseudo-philosophical reasons for preferring it to projective Geometry, however, I by no means agree." (PoM)



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IMPORTANCE OF RUSSELL

Russell took the mathematical work and turned it into a philosophical argument

 qualitative, descriptive geometry is the most important, primary one

this geometry is nowadays known as affine



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WHAT IS AFFINE GEOMETRY?

DEFINITION

An (n-dimensional) affine transformation of \mathbb{R}^n is a function $\tau : \mathbb{R}^n \to \mathbb{R}^n$ of the form

$$\tau(\mathbf{x}) = \mathbf{A}\mathbf{x} + \mathbf{b},$$

where **A** is an invertible $n \times n$ matrix and $b \in \mathbb{R}^n$.

We say that two regions are affine-equivalent if there is an affine transformation from one region to another (this notion naturally extends to sequences of regions). Properties unchanged under affine tranformations are called affine-invariant.



AFFINE TRANSFORMATIONS CTD.

THEOREM

An affine transformation maps straight lines to straight lines, preserves parallelism and ratios of lengths along parallel straight lines. The set of affine transformations forms a group under the operation of composition of functions.



Image source: J.P. de Vries, Object Recognition: A Shape-Based Approach Using Artificial Neural Networks



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AFFINE PROPERTIES

DEFINITION

A set $S \in \mathbb{R}^n$ is called *convex* if for all $\lambda_1, \lambda_2 \in \mathbb{R}$, such that $\lambda_1, \lambda_2 \ge 0$ and $\lambda_1 + \lambda_2 = 1$ and for all $x \in S$,

$$\lambda_1 x + \lambda_2 y \in S.$$

Convexity is an affine-invariant property. (So is set inclusion.)



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- The Axioms of Descriptive Geometry
- such ideas were developed further in 1970s



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- more that 100 years after the publication of Russell's *The Foundations of Geometry*, a group of CS researchers took interest in a similar approach to geometry
- the field they established began to be known as Qualitative Spatial Reasoning
- the emphasis was on formalising and analysing commonsensical, non-numerical part of geometry
- the hope: to mimic human-like spatial reasoning in formal settings



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regions rather than points became the primitive entities

- a number of logical formalisms were proposed involving qualitative relations among regions
- Region Connection Calculus and its derivative RCC8 are perhaps the best-known ones
- an attempt has been made to connect to previous developments, including Whitehead's ideas



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FEW BONES TO PICK

Russell's contribution was not recognized

- the entire area focused on logical systems with topological interpretations
- only a small portion of research devoted to affine spatial logics



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AFFINE SPATIAL LOGICS — THE SETUP

DEFINITION

Let *S* be a subset of some topological space. We denote the interior of *S* by S^0 and the closure of *S* by S^- . *S* is called regular open if $S = (S)^{-0}$.

The following result is standard.

PROPOSITION

The set of regular open sets in *X* forms a Boolean algebra RO(X) with top and bottom defined by 1 = X and $0 = \emptyset$, and Boolean operations defined by $a \cdot b = a \cap b$, $a + b = (a \cup b)^{-0}$ and $-a = (X \setminus a)^0$.



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- by a regular open rational polygon we mean a Boolean combination in RO(ℝ²) of finitely many half-planes bounded by lines with rational coefficients in ℝ².
- ► we denote the set of all regular open rational polygons in ℝ² by *ROQ*(ℝ²).
- ▶ $ROQ(\mathbb{R}^2)$ is a Boolean subalgebra of $RO(\mathbb{R}^2)$.
- the notion of regular open rational polygon can be easily extended to that of a polytope, when considering dimensions greater than 2. In general, we write *ROQ*(ℝⁿ), n ∈ N, to denote the set of all regular open rational polytopes of dimension n.



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FIRST-ORDER AFFINE SPATIAL LOGICS

We are interested in structures defined as follows:

DEFINITION Let $\mathfrak{M}^n = \langle ROQ(\mathbb{R}^n), \mathfrak{conv}^{\mathfrak{M}}, \leq^{\mathfrak{M}} \rangle$, where

$$\leq^{\mathfrak{M}} = \{ \langle a, b \rangle \in ROQ(\mathbb{R}^n) \times ROQ(\mathbb{R}^n) \mid a \subseteq b \}; \\ \mathfrak{conv}^{\mathfrak{M}} = \{ a \in ROQ(\mathbb{R}^n) \mid a \text{ is convex} \}.$$

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$$\mathfrak{M}^3 = \langle \textit{ROQ}(\mathbb{R}^3), \mathfrak{conv}^\mathfrak{M}, \leq^\mathfrak{M} \rangle$$



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 $\mathfrak{conv}(x) \wedge \mathfrak{conv}(-x)$

$$\mathfrak{hs}_n(x_1,\ldots,x_n):=\bigwedge_{\substack{1\leq i\leq n}}\mathfrak{conv}(x_i)\wedge\mathfrak{conv}(-x_i)\wedge\bigwedge_{\substack{1\leq i\leq n,\\1\leq j\leq n,\\i\neq j}}x_i\neq x_j\wedge x_i\neq -x_j$$



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$$\mathfrak{hs}_2(x,y) \land ((x \cdot y = 0 \lor x \cdot -y = 0) \lor (-x \cdot y = 0 \lor -x \cdot -y = 0))$$

$$\mathfrak{hs}_2(x,y) \wedge \neg ((x \cdot y = 0 \lor x \cdot -y = 0) \lor (-x \cdot y = 0 \lor -x \cdot -y = 0))$$



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$\operatorname{line}(y_1, y_2) \wedge \operatorname{line}(y_1, y_3) \wedge \operatorname{line}(y_2, y_3)$

1. a sheaf 2. a prism 3. a corner



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Coordinatising Affine Spatial Logics



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$$\neg \exists x \neg \exists y \neg \exists z (((x = y_1 \lor x = -y_1) \land (y = y_2 \lor y = -y_2) \land (z = y_3 \lor z = -y_3))$$
$$\land (x \cdot y \cdot z = 0))$$

corner(x, y, z)

 $\mathfrak{frame}(y_1, y_2, y_3, y') :=$ $\mathfrak{corner}(y_1, y_2, y_3) \land \mathfrak{line}(y_1, y') \land \mathfrak{line}(y_2, y') \land \mathfrak{line}(y_3, y')$



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$\overline{\textbf{OA}} + \overline{\textbf{OB}} = \overline{\textbf{OC}}$

$\overline{\textbf{OA}}\cdot\overline{\textbf{OB}}=\overline{\textbf{OC}}$



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THEOREM

Assuming the coordinate frame setup above and all the introduced shorthands, let *m* be a line crossing one of the axes at a point **M**. Then there exists a formula satisfiable in \mathfrak{M}^3 if and only if $\overline{\mathbf{OM}} = n\overline{\mathbf{OI}}, n \in \mathbb{Q}$.



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THEOREM

Fix a tuple satisfying the frame (y_1, y_2, y_3, y') formula. Let $h, h' \in ROQ(\mathbb{R}^3)$ be half-spaces. Then there is a formula ϕ satisfiable in \mathfrak{M}^3 , such that (1) h satisfies this formula and (2) if h' satisfies the formula, then h' = h.



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THEOREM Every $r \in ROQ(\mathbb{R}^3)$ satisfies an affine-complete formula in \mathfrak{M}^3 .



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- affine geometry remains closer to our every-day experiences than projective geometry (or topology for that matter) and still it retains the status of non-qualitative
- despite being singled out as an independent entity relatively recently, affine geometry seems to have played an important role since the early days of formal geometry
- finally, affine spatial logics proved to be really expressive, more so than other spatial systems
- the next step: axiomatising the three-dimensional affine spatial logic



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Thank you

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